PID in the NICA experiment using MVA

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Signal dE/dx vs p in the MPD-TPC detector for Bi-Bi collisions of $\sqrt{s}=11$ GeV,



- Detector: MPD (TPC, TOF)
- Input file: rectestf140.root file (DST)
- Event generator: UrQMD
- Bi-Bi a 11 GeV (MB)
- of events: 10k
- Macro: CompareSpectra.C, anaDST.C

We read the reconstruction files from the tree in the *.root* file with the information of events and tracks:

```
for (Int_t nf = 0; nf <1; nf++){ // files name rectestf14#.root, from nf to nf++
    // Input files
    sprintf(name, "/home/julio/Research/Taller3/12_PID-with-different-detectors/rectestf14%d.root",nf);
    cout <<" Openning file " << name << endl;
    TString fileName = name;
    // Define Chain to tree mpdsim
    TChain *mpdSim = new TChain("mpdsim");
    mpdSim->Add(fileName); //put the filename
    // Set branches
    MpdEvent *mpdEvents = NULL;
    mpdSim->SetBranchddress("MPDEvent.", &mpdEvents);
    TEranch *DSTBranch = mpdSim->GetBranch("MPDEvent.");
    TClonesArray *mcTracks = NULL;
    mpdSim->SetBranchAddress("MCTrack", &mcTracks);
    TBranch *MCBranch = mpdSim->GetBranch("MCTrack");
```

```
Int t mcNtracks = mcTracks->GetEntries();
//cout << " *** Event # " << i+1 << " No. of MC tracks = " << mcNtracks << endl;</pre>
for (Int t j = 0; j < mcNtracks; j++){</pre>
  Ntr++:
  MpdMCTrack *mctrack = (MpdMCTrack*)mcTracks->At(j);
  MotherID = mctrack->GetMotherId();
  PDGID = mctrack->GetPdgCode();
  PtMC = mctrack->GetPt();
  PtMC = TMath::Abs(PtMC);
  Pxyz.SetXYZ(mctrack->GetPx(),mctrack->GetPy(),mctrack->GetPz());
  EtaMC = Pxyz.PseudoRapidity();
  NMC++;
  hEtaMC->Fill(EtaMC):
  hPtMC->Fill(PtMC);
} //end MC track loop
```

```
// MPD tracks loop
TClonesArray *mpdTracks = mpdEvents->GetGlobalTracks();
Int t mpdNtracks = mpdTracks->GetEntriesFast():
for (Int t k = 0; k < mpdNtracks; k++){</pre>
  Ntrmpd++;
  MpdTrack *mpdtrack = (MpdTrack*)mpdTracks->UncheckedAt(k):
  ID = mpdtrack->GetID();
  MpdMCTrack *mctrack1 = (MpdMCTrack*)mcTracks->UncheckedAt(ID);
  MotherID = mctrack1->GetMotherId():
  Pt = mpdtrack->GetPt():
  Pt = TMath::Abs(Pt):
  Eta = mpdtrack->GetEta();
  N++;
  hEta->Fill(Eta):
  hPt->Fill(Pt);
```

```
Px = mpdtrack->GetPx();
  Py = mpdtrack->GetPy();
  Pz = mpdtrack->GetPz();
  P = TMath::Sqrt(Pz*Pz + Px*Px + Py*Py);
  dEdx = mpdtrack->GetdEdXTPC();
  hEta->Fill(Eta);
  hPt->Fill(Pt);
  hdEdx->Fill(dEdx);
  hdEdxP->Fill(P,dEdx);
} // MPD track loop
hN->Fill(N);
```

The probability of a particle i, if s signal is observed,

$$P(i|s) = \frac{r(s|i)C_i}{\sum_k r(s|k)C_k}$$

r(s|i) probability density function of the observed signal s of the detector, if a particle $i(e, \mu, \pi, K, p, ...)$ is detected.

 C_i frecuency of the observed particle.

Using the tracks information of the Monte Carlo (PDGID)

```
if (TMath::Abs(PDGID) == 211 ){ //pion
 NDi++:
 hpiEta->Fill(Eta);
 hpiPt->Fill(Pt):
 Px = mpdtrack->GetPx();
 Pv = mpdtrack->GetPv():
 Pz = mpdtrack->GetPz();
 P = TMath::Sqrt(Pz*Pz + Px*Px + Py*Py);
 dEdx = mpdtrack->GetdEdXTPC();
 hpidEdx->Fill(dEdx);
 hpidEdxP->Fill(P.dEdx):
 hpiEtaMC->Fill(EtaMC);
 hpiPtMC->Fill(PtMC):
 M2 = mpdtrack->GetTofMass2();
 hpiM2->Fill(M2);
```



Figure 1: dE/dx en TPC para 10 mil eventos tomando partículas primarias y secundarias.

```
//pion
Double_t parpi[6];
TF1* fitgausspi = new TF1("fitgausspi","gaus(0)",1000.,2900.00);
TF1* fitlandaupi = new TF1("fitlandaupt","landau(0)",2900.00,5000.);
TF1* fitlotalpi = new TF1("fitlotalpi","gaus(0)+landau(3)",1000.,5000.);
fittotalpi->SetLineColor(2);
hpidEdx->Fit(fitgausspi,"R");
hpidEdx->Fit(fitlandaupi,"R+");
fitgausspi->GetParameters(&parpi[0]);
fitlotalpi->SetParameters(&parpi[3]);
fittotalpi->SetParameters(parpi);
hpidEdx->Fit(fittotalpi,"R");
```

dE/dx histogram and fit



Frequency of the particle



Probability with bayesian model

```
Int t Cp = 332:
Int t Cpi = 52:
Int t Ck = 1626:
Int t i;
parp[0] = 2.26248e+02:
parp[1] = 3.53863e+03:
parp[2] = 5.27756e+02;
parp[3] = 4.56528e+03;
parp[4] = 5.09123e+03:
parp[5] = 4.68042e+02:
parpi[0] = 4.08121e+04;
parpi[1] = 3.40529e+03;
parpi[2] = -2.19923e+02:
parpi[3] = 1.12808e+06:
parpi[4] = 2.86475e+03:
parpi[5] = -2.12680e+02;
park[0] = 5.75678e+03:
park[1] = 4.07096e+03:
park[2] = 5.22213e+02:
park[3] = 9.05859e+03;
park[4] = 3.38738e+03;
park[5] = 2.72836e+02:
```

```
TFormula *rp = new TFormula("rp","[0]*TMath::Exp(-0.5*TMath::Power((x-[1])/[2],2))
+ [3]*TMath::Exp(-0.5*TMath::Power((x-[4])/[5],2)) + [6]*TMath::Exp(-0.5*TMath::Power((x-[7])/[8],2))
+ [9]*TMath::Landau(x,[10],[11])"):
 TFormula *rpi = new TFormula("rpi","[0]*TMath::Exp(-0.5*TMath::Power((x-[1])/[2],2))
+ [3]*TMath::Exp(-0.5*TMath::Power((x-[4])/[5],2)) + [6]*TMath::Exp(-0.5*TMath::Power((x-[7])/[8],2))
+ [9]*TMath::Landau(x.[10].[11])"):
  TFormula *rk = new TFormula("rk","[0]*TMath::Exp(-0.5*TMath::Power((x-[1])/[2],2))
+ [3]*TMath::Exp(-0.5*TMath::Power((x-[4])/[5].2)) + [6]*TMath::Exp(-0.5*TMath::Power((x-[7])/[8].2))
+ [9]*TMath::Landau(x,[10],[11])");
 rp->SetParameters(parp):
 rp->Print();
 rpi->SetParameters(parpi);
 rpi->Print();
 rk->SetParameters(park);
 rk->Print():
 double t crp. crpi. crk:
 double t Probp, Probpi, Probk;
  for(i=0;i<15000;i++){</pre>
    fscanf(fp,"%lf",&dEdx[i]);
    crp = rp->Eval(dEdx[i]);
    crpi = rpi->Eval(dEdx[i]);
    crk = rk->Eval(dEdx[i]):
    Probp = (crp*Cp)/(crp*Cp + crpi*Cpi + crk*Ck);
    Probpi = (crpi*Cpi)/(crp*Cp + crpi*Cpi + crk*Ck):
    Probk = (crk*Ck)/(crp*Cp + crpi*Cpi + crk*Ck);
    fprintf(fp2, "%f %f %f \n", Probp, Probpi, Probk);
                                                                                                      14
```

Representation of the type of the particle for a neural network output with three classes,

| 0 | 1 | 2 | Particle |
|---|---|---|-------------|
| 0 | 0 | 1 | K^{\pm} |
| 0 | 1 | 0 | π^{\pm} |
| 1 | 0 | 0 | р |

We take the reconstruction data for a selected momentum range, and choose the features of the model,

```
model <- mlp(
    x,
    y,
    size = 5,
    maxit = 100,
    initFunc = "Randomize_Weights",
    initFuncParams = c(-0.3, 0.3),
    learnFunc = "Std_Backpropagation",
    learnFuncParams = c(0.2, 0),
)</pre>
```

We can predict the the probability by particle type

predict(model, newdata = z, type = "Prob")

| ID | ProbP | ProbPi | ProbK |
|----|---------|---------|---------|
| 1 | 0.00263 | 0.01511 | 0.99023 |
| 2 | 0.25084 | 0.00266 | 0.69811 |
| 3 | 0.03034 | 0.09871 | 0.90590 |

We take a threshold value of probability (0.5) to compare with the probability of the prediction,

| | VP % | FN % | VN % | FP % |
|-------------|-------|-------|-------|------|
| р | 96.22 | 3.78 | 98.18 | 1.82 |
| π^{\pm} | 90.38 | 9.62 | 94.89 | 5.11 |
| Κ± | 85.72 | 14.28 | 95.15 | 4.85 |

Comparing models

For the dataset $0.2 \leq P < 1.0$

| Bayesiano | MLP | |
|-----------|--|--|
| 83.84 % | 99.18 % | |
| 16.16 % | 0.82 % | |
| 95.08 % | 99.52 % | |
| 4.92 % | 0.48 % | |
| | Bayesiano 83.84 % 16.16 % 95.08 % 4.92 % | |

For the dataset $1.8 \le P < 2.6$

| | Bayesiano | MLP | |
|----|-----------|---------|--|
| VP | 0.8 % | 90.38 % | |
| FN | 99.2 % | 9.62 % | |
| VN | 99.37 % | 94.89 % | |
| FP | 0.63 % | 5.11 % | |