

Luminosity determination with ALICE at the LHC

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For the ALICE Collaboration



ALICE



Outline

1. Introduction

- Luminosity
- van der Meer (vdM) scan

2. vdM Analysis

- Overview
- Process and corrections
- Long-term stability and consistency
- Run 2 results

Introduction

- **Luminosity**

- For any cross-section measurement,

$$\sigma = N / L_{int}$$

a. σ : cross-section of a physics process

b. N : yield of the physics process

c. $L_{int} = \int L(t) dt$: integrated luminosity, where L is the **instantaneous luminosity**

ALICE J/ψ and $\psi(2S)$ in pp, arXiv:1702.00557 (2017)

Source	$\sqrt{s} = 13$ TeV		$\sqrt{s} = 5.02$ TeV	
	J/ψ (%)	$\psi(2S)$ (%)	J/ψ (%)	$\psi(2S)$ (%)
Branching ratio	0.6	11	0.6	11
Luminosity	3.4	3.4	2.1	2.1
Signal extraction	3 (3–8)	5 (5–9)	3 (1.5–10)	8
MC input	0.5 (0.5–1.5)	1 (0.5–4)	2 (0.5–2.5)	2.5
MCH efficiency	4	4	1	1
MTR efficiency	4 (1.5–4)	4 (1.5–4)	2 (1.5–2)	2
Matching	1	1	1	1

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- Two possible approaches to measure the luminosity during physics data-taking

a. $L = \frac{R_{ref}}{\sigma_{ref}}$: by using the cross-section of a known physical process (e.g., Z^0 boson)

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b. $L = \frac{R_{vis}}{\sigma_{vis}} = \frac{f_{rev} \mu_{vis}}{\sigma_{vis}}$: by using a **visible cross-section** (σ_{vis})

b-1. f_{rev} : accelerator revolution frequency

b-2. μ_{vis} : average # of “visible” interactions per bunch crossing

b-3. σ_{vis} : “visible” cross-section measured experimentally

b-4. **The method used in ALICE**

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Introduction

- **Luminosity (continue)**

- From an experimental point of view, L for a colliding bunch pair is:

$$L = \frac{R_{vis}}{\sigma_{vis}} = \frac{f_{rev} \mu_{vis}}{\sigma_{vis}} = f_{rev} N_1 N_2 \cdot \iint \rho_1(x, y) \rho_2(x, y) dx dy$$

- N_1, N_2 : bunch intensity
- ρ : particle density distribution in transverse plane
- $\iint \rho_1 \rho_2 dx dy$: beam overlap integral



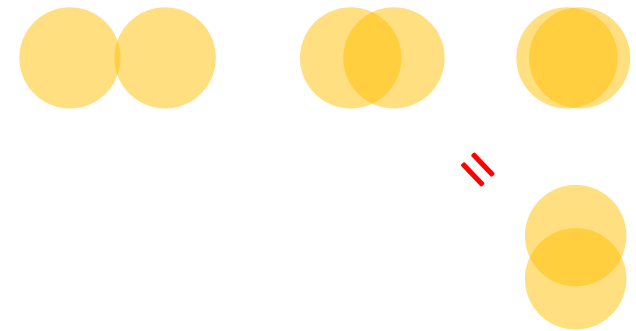
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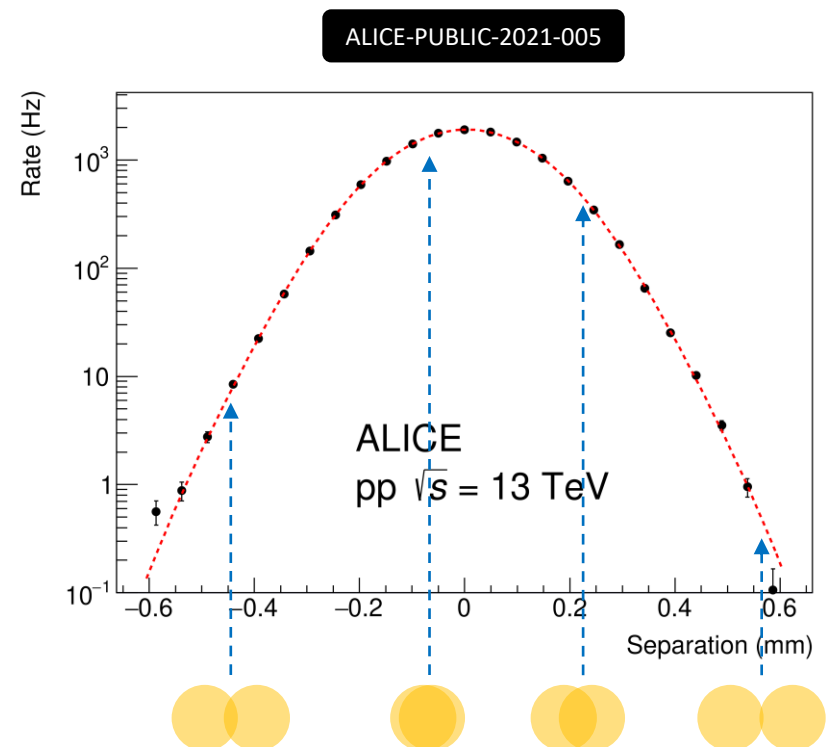
- Assuming **factorization stands**, then L can be written as:

$$L = \frac{f_{rev} N_1 N_2}{h_x h_y}$$

- $1/h_x$: $\int \rho_{1,x}(x) \rho_{2,x}(x) dx$, $h_x(y)$: **effective beam overlap width** in x (y) direction
- $N_1 N_2$: measured by using accelerator instrumentation
- $h_x h_y$:
 - Can be derived from nominal machine parameters but large uncertainty (> 10%)
 - Require dedicated session for direct & precise measurement: **van der Meer (vdM) scan**

Introduction

- **vdM scan**
 - Dedicated measurement of μ_{vis} vs. beam separation
 - a. Estimate visible rate per bunch crossing
 - b. Adjust separation distance of each bunch crossing:
scan horizontal (x) or vertical (y) direction,
while fixing the other direction in the head-on position
 - c. “Tailored” running conditions are preferred:
low μ_{vis} , low intensity, well-spaced bunches...
 - d. 1-2 sessions per year

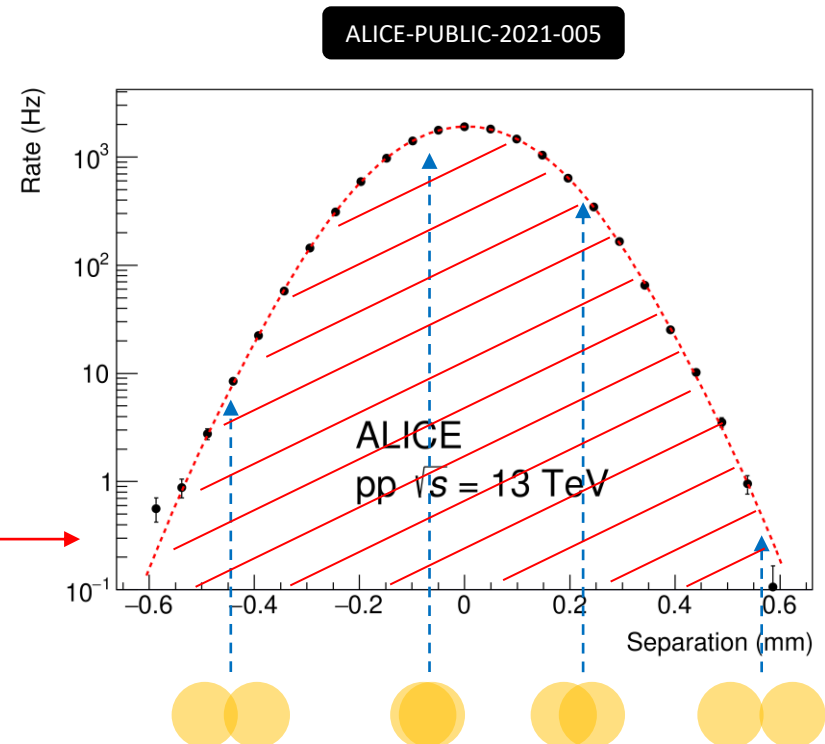


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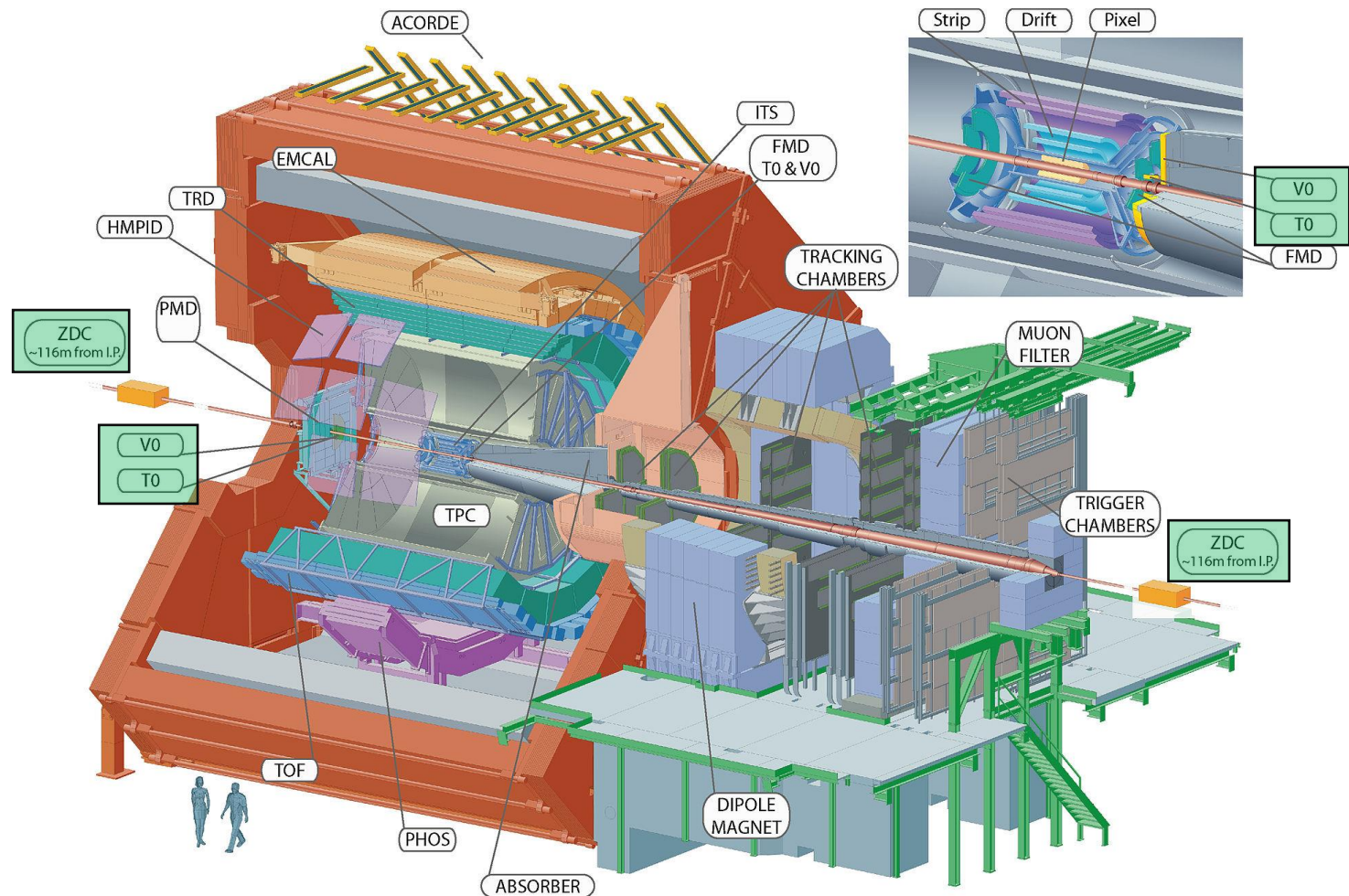
$$L = \frac{f_{rev} N_1 N_2}{h_x h_y}$$

$h_{x(y)}$: the area under the curve normalized by its peak value, obtained during the horizontal (vertical) scan



Introduction

- **vdM scan related apparatus in ALICE**



Introduction

- **vdM scan related apparatus in ALICE**

- All detectors are built as a pair WRT the IP

(* ATLAS (A-) side or CMS (C-) side)

- a. V0

- a-1. Two scintillator arrays

- a-2. $2.8 < \eta < 3.7$, $-3.7 < \eta < -1.7$

- b. T0

- b-1. Two Cherenkov detector arrays

- b-2. $4.61 < \eta < 4.92$, $-3.28 < \eta < -2.97$

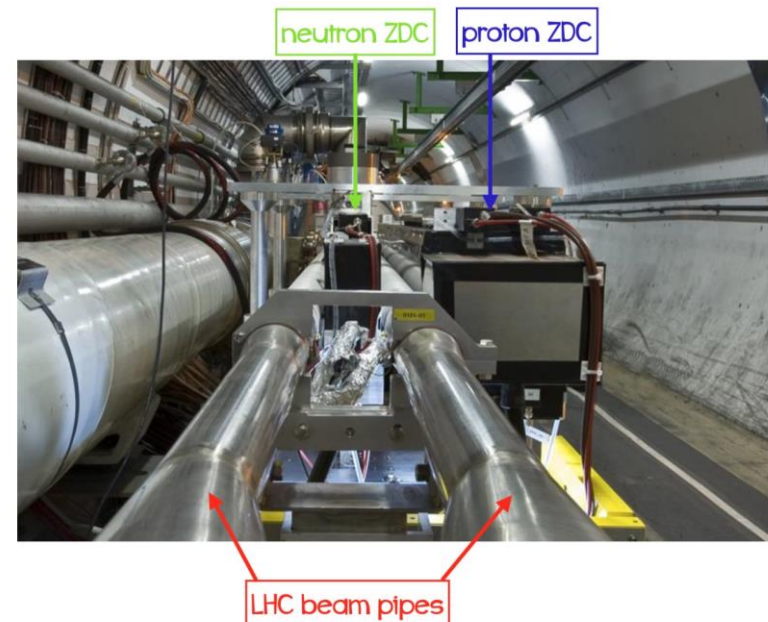
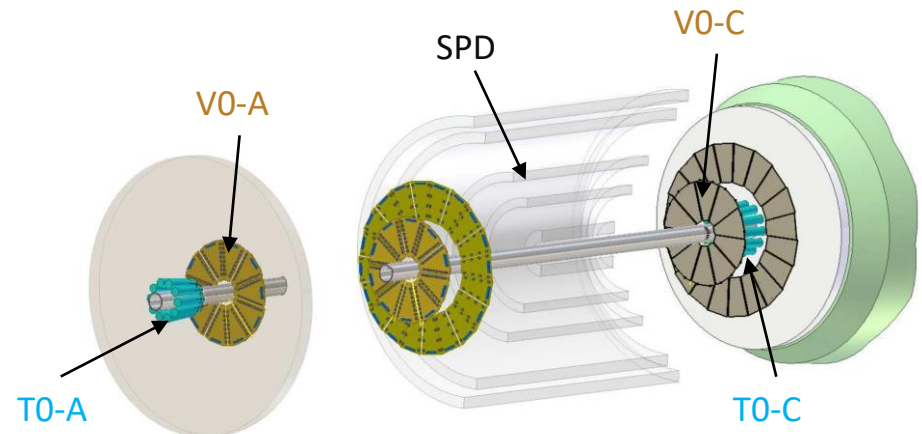
- c. ZN (Neutron ZDC)

Two quartz-fiber spaghetti calorimeters at $z = \pm 114$ m

- Signal condition in vdM scan by collision system

- a. pp, p-Pb: coincidence of A- and C- side in T0, V0

- b. Pb-Pb: Amplitude trigger (V0), Single-neutron trigger (ZN)



vdM analysis

In ALICE

vdM analysis Overview

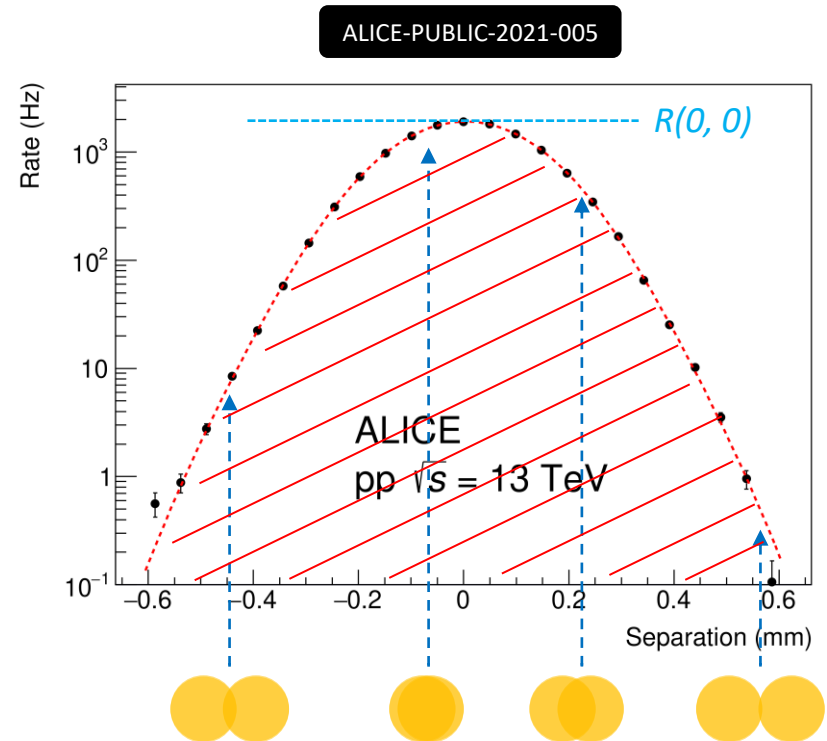
- **vdM analysis in ALICE**

- Goal: determine visible cross-section (σ_{vis})

$$\sigma_{vis} = R(0, 0)/L,$$

$$L = f_{rev} N_1 N_2 / h_x h_y$$

1. $N_1 N_2$: beam intensities of colliding bunches
(* Measured by using LHC instrumentation)
2. Separation
3. R : (visible) rate measured in ALICE
(* $R(0, 0)$: head-on (highest) rate)
4. $h_x h_y$: effective beam overlap width
(* Area under the curve, divided by $R(0, 0)$)
5. Compute σ_{vis}



vdM analysis Overview

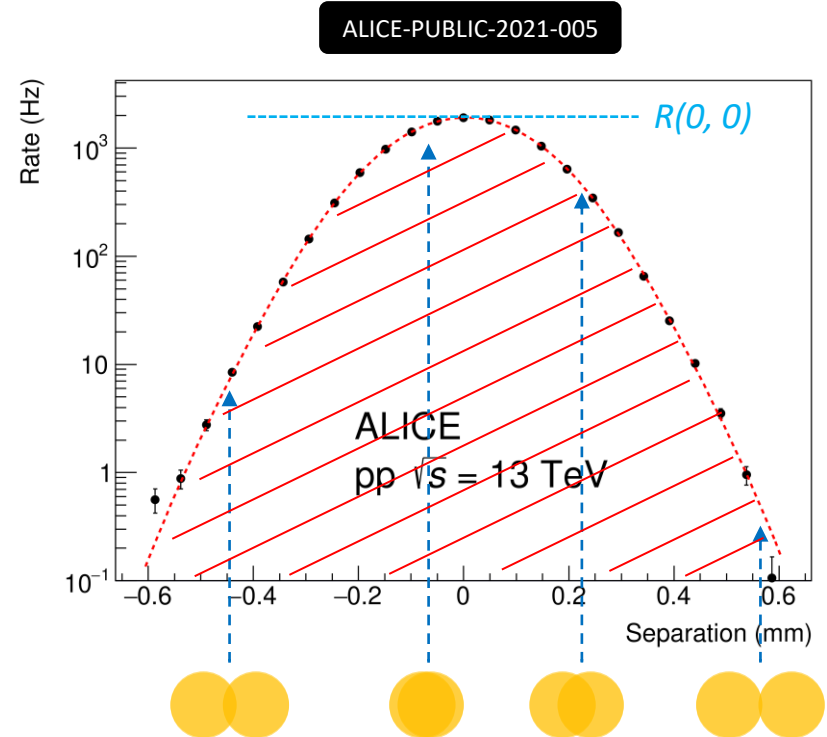
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For a bunch crossing of a scan:
repeat for all bunches and scans

vdM Analysis Process and corrections

1. Intensity

- Measured with LHC (DCCT, FBCT) or ATLAS (BPTX) instrumentation
DCCT for total beam current (normalization) and FBCT/BPTX for relative bunch intensity

- Correction for satellite/ghost

- One bunch slot = 10 buckets = 25 ns

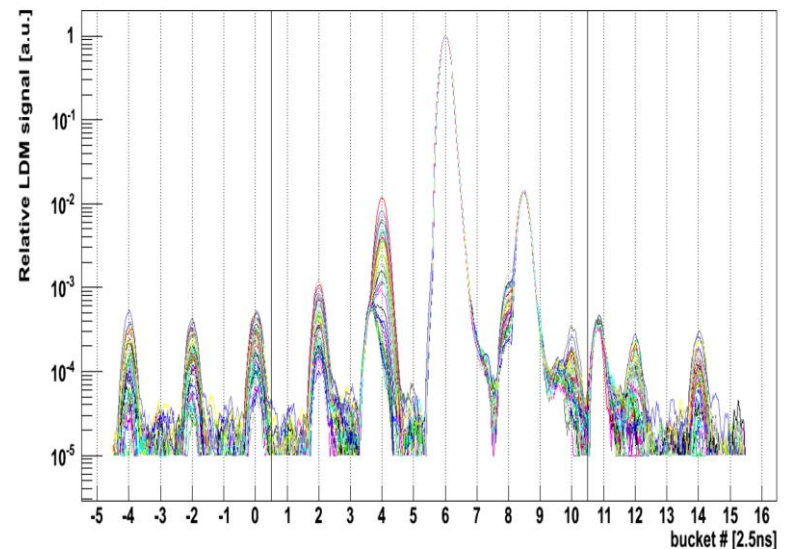
Most of the ions in a bunch are well placed in a 2.5 ns wide central bucket of the RF system

- Satellite:** ions placed “outside the central bucket”
- Ghost:** ions placed in the slots “supposed to be empty”
- DCCT measures charge of all buckets:
contribution from satellite/ghost must be removed
(i.e., $N_{bunch} = N_{tot} - N_{sat} - N_{ghost}$)
- Large correction for Pb-Pb:
correction can reach few % level

- However, **either pp or Pb-Pb**, the final effect on σ_{vis} uncertainty is **a few per-mill (‰) level**

CERN-ATS-Note-2013-034 TECH

Fill 2852, Beam 1, 2012-07-17 01:34, All nominally filled slots



vdM Analysis Process and corrections

2. Separation

- Start with the “nominal” separation

The separation info provided by the LHC

- Corrections on nominal separation:

a. LSC (length-scale calibration):

measure the conversion factor

between nominal and actual beam position

b. Orbit drift correction (ODC):

b-1. A bunch’s orbit can vary from the reference beam orbit

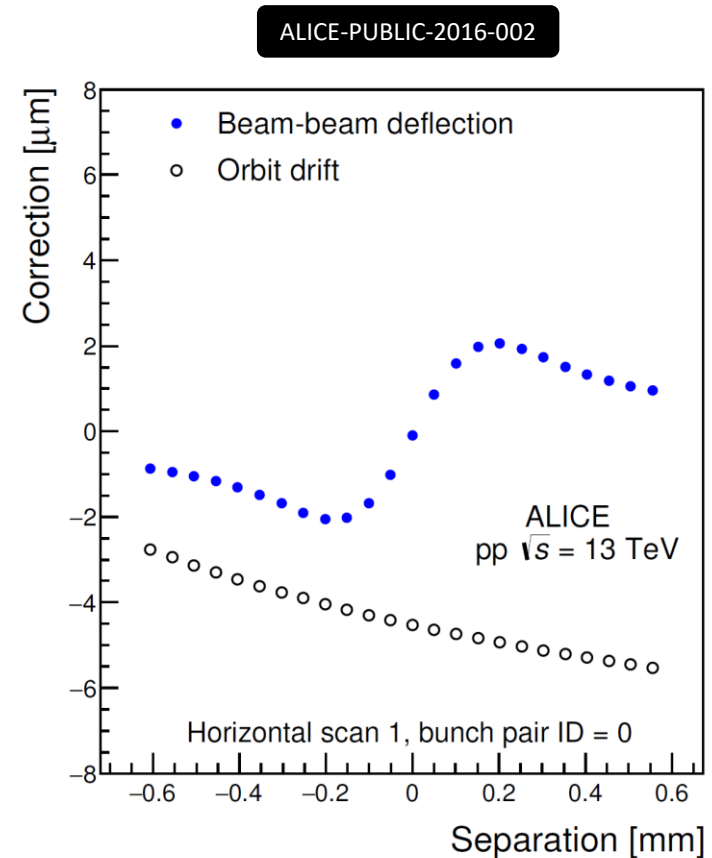
b-2. Time-dependent

c. Beam – Beam deflection (BBD):

c-1. Each bunch (beam) is electrically charged

c-2. Two beams exert a repulsive force upon each other:

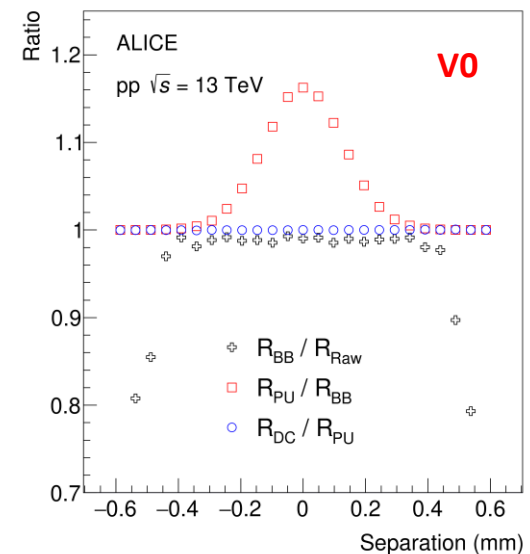
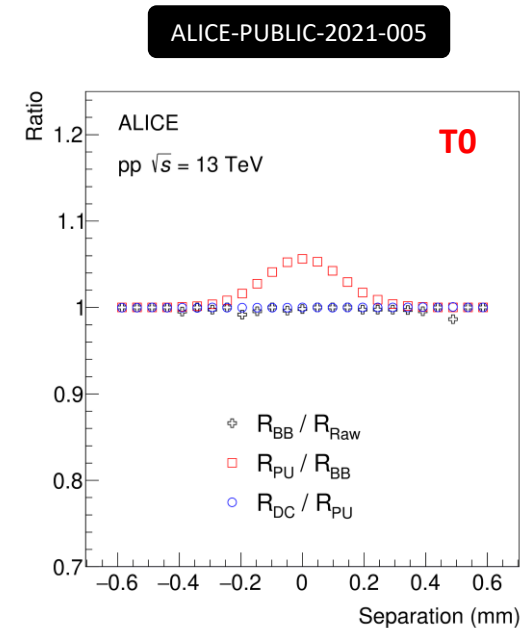
the repulsion affects the separation



vdM Analysis Process and corrections

3. Rate

- Measured with ALICE detectors (V0, T0, and ZN)
- Corrections on raw trigger rate:
 - a. Backgrounds (BB):
 - a-1. Beam-gas, Satellites, After-pulsing
 - a-2. Use timing cut for the removal
 - b. Pile-up (PU):
 - b-1. Effect of multiple collisions per bunch crossing
 - b-2. Corrections based on the Poisson distribution of coincidences
 - c. Intensity decay (DC)
- Note that explanations here are written WRT pp, but equivalent procedures exist in Pb-Pb



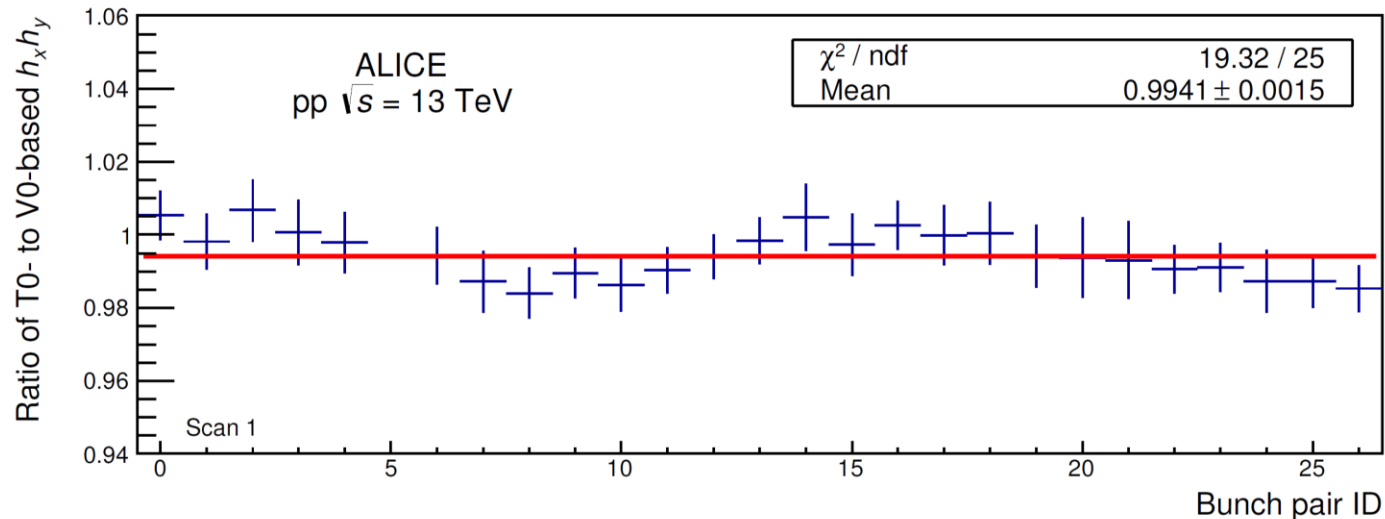
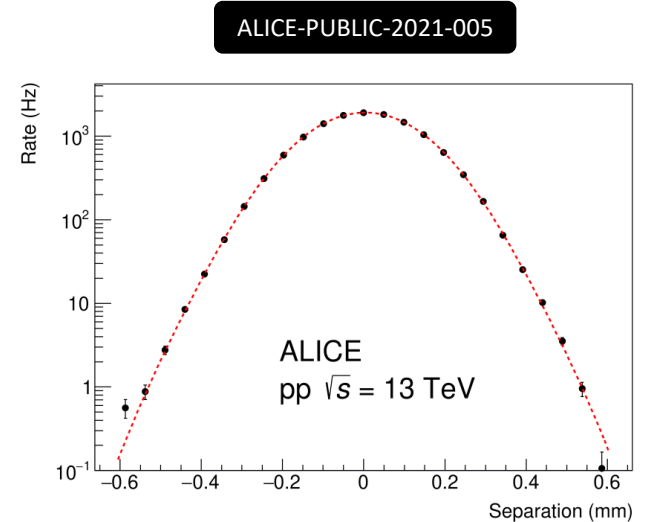
vdM Analysis Process and corrections

4. Effective beam width ($h_x h_y$)

- Bunch by Bunch $h_x h_y$:
 - a. Estimated by fitting the measured rate vs. separation
 - b. Standard fit function in pp: Gaussian x partial pol6

$$A(x) = N \cdot \exp\left(-\frac{(x - \mu)^2}{2\sigma}\right) \cdot (1 + p_2(x - \mu)^2 + p_4(x - \mu)^4 + p_6(x - \mu)^6)$$

- c. Final crosscheck by using the ratio of $h_x h_y$ from different detectors



ALICE-PUBLIC-2016-002

vdM Analysis Process and corrections

4. Effective beam width ($h_x h_y$) (continue)

– Non-factorization

a. Let's take a few steps back:

$$L = f_{rev} N_1 N_2 / h_x h_y = f_{rev} N_1 N_2 \cdot \iint \rho_1(x, y) \rho_2(x, y) dx dy,$$

only if **factorization stands**

b. If factorization is broken,

b-1. The motion in x direction also affects the y

b-2. 3D convolution on two colliding bunches' overlapped region (aka luminous region)

c. Specific data taken for study:

with offset in x (y)

d. Compute correction factors:

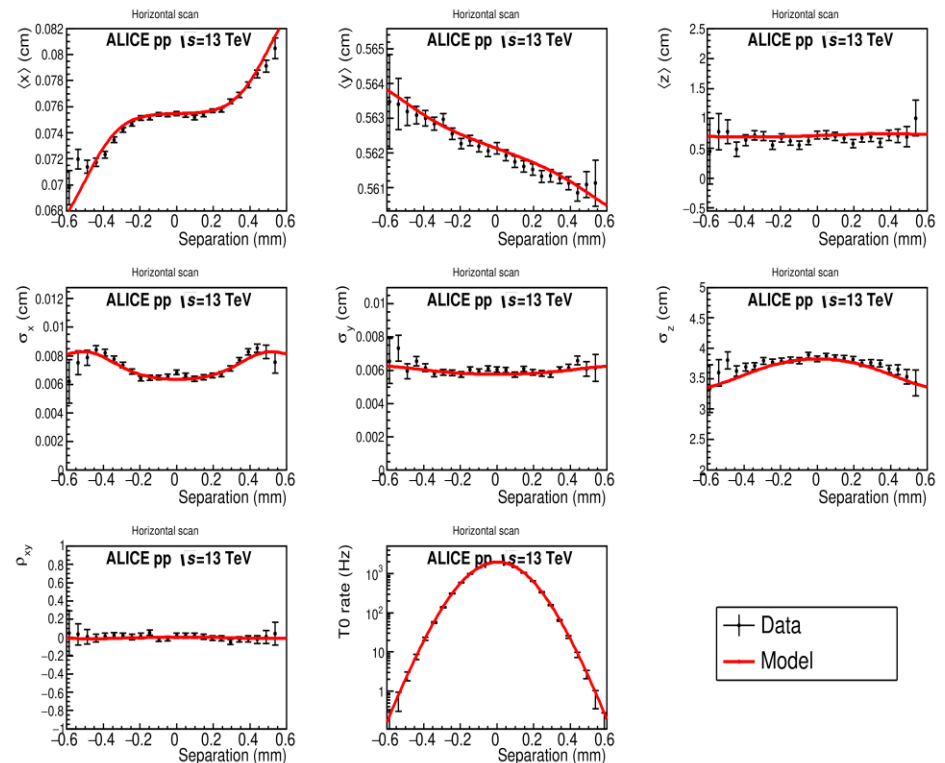
measure luminous region by 3D vertexing

based on barrel detectors

e. Overall uncertainty on σ_{vis} :

< 0.5% for pp and < 1.1% for Pb-Pb

ALICE-PUBLIC-2021-005

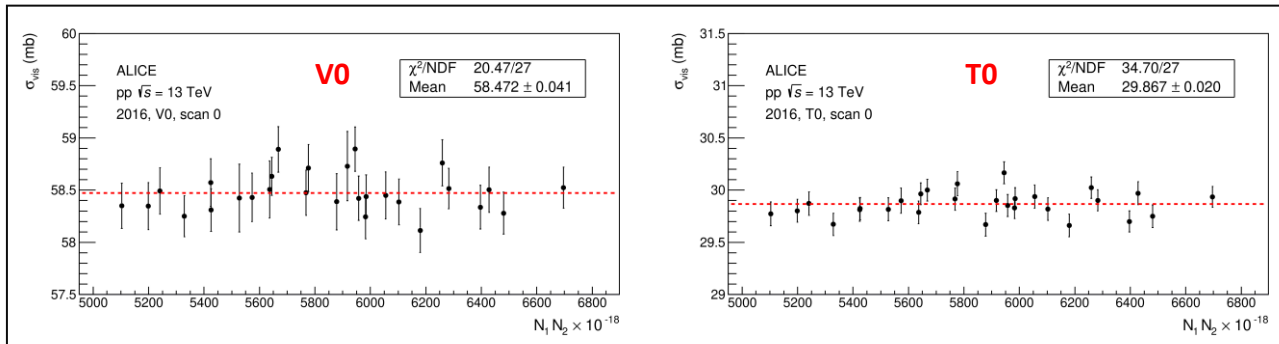


vdM Analysis Process and corrections

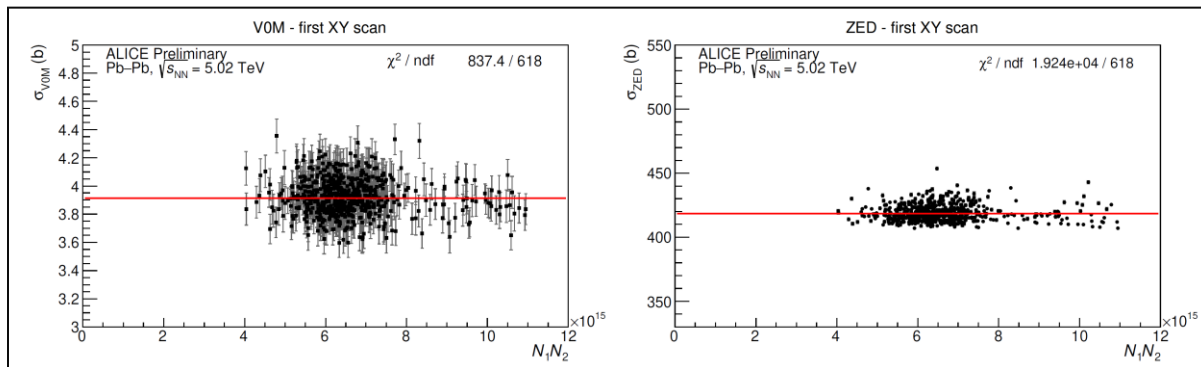
5. Compute σ_{vis}

– Extracting final σ_{vis}

- σ_{vis} is computed for each bunch crossing
- Get average σ_{vis} of a given scan (either 0 or 1) by constant fit
- Final σ_{vis} is the average of the two scans



pp $\sqrt{s} = 13$ TeV
ALICE-PUBLIC-2021-005

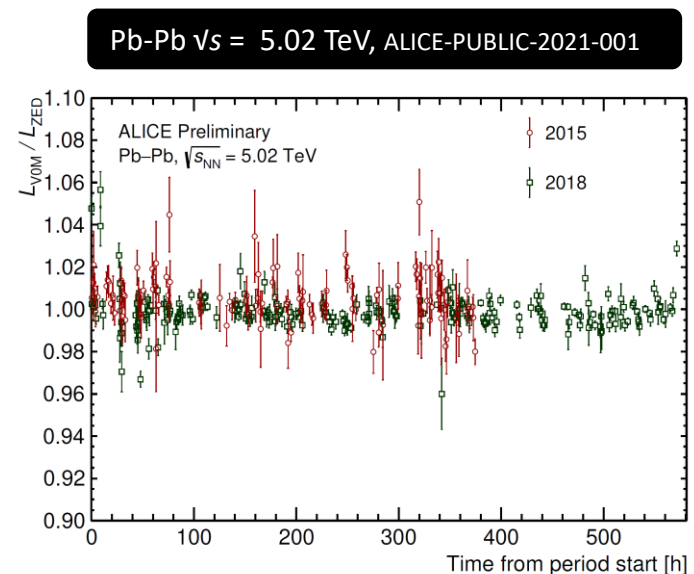
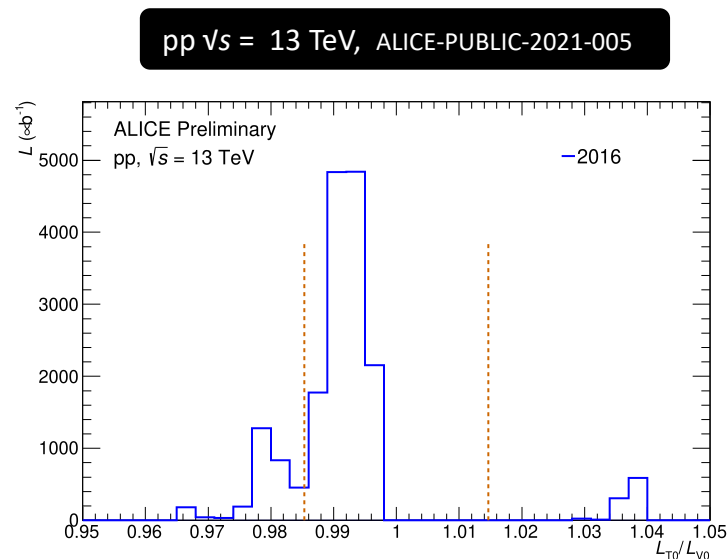


Pb-Pb $\sqrt{s} = 5.02$ TeV
ALICE-PUBLIC-2021-001

vdM Analysis Long-term stability and consistency

- **Validity throughout the runs**

- The luminosity of a physics run = Luminosity trigger counts of the run / σ_{vis}
- The stability and consistency of ALICE detectors (V0, T0, and ZN)
 - a. Evaluation by the ratio of “T0-based / V0-based luminosity” (or V0/ZN, in Pb-Pb)
 - b. Estimate the uncertainty by using RMS (WRT unity) over the runs
- The largest uncertainty source in pp (2016 - 2018)



vdM Analysis

Run 2 results

• Table of systematic errors

- Presenting only recent results (pp/Pb-Pb 2015-2018): check backup for others
- Source of the largest error is different for each system: stability for pp and non-factorization for Pb-Pb
- In pp, one must consider the correlation across the years:
the overall uncertainty of the luminosity for the analyses use data from all 3 years $\sim 1.6\%$

<u>pp vs = 13 TeV (2016, 2017, and 2018)</u>				
Uncertainty	2016	2017	2018	Correlated?
	T0 V0	T0 V0	T0 V0	
Statistical	0.05% 0.05%	0.07% 0.07%	0.05% 0.05%	No
Bunch intensity				
Beam current normalisation	0.5%	0.5%	0.4%	Yes
Relative bunch populations	0.1%	0.3%	0.1%	No
Ghost and satellite charge	< 0.1%	< 0.1%	< 0.1%	No
Non-factorisation	0.5%	0.2%	0.4%	Yes
Length-scale calibration	0.2%	0.3%	0.3%	No
Beam-beam effects	0.3%	0.3%	0.3%	Yes
Orbit drift	0.1%	0.1%	0.2%	No
Magnetic non-linearities	0.1%	0.2%	0.2%	Yes
Beam centring	< 0.1%	< 0.1%	0.1%	No
Luminosity decay	0.5%	0.5%	0.3%	No
Background subtraction	0.1% 0.6%	0.1% 0.8%	0.1% 0.7%	Yes
Pile-up	0.1% < 0.1%	0.5%	0.2% < 0.1%	Yes
Fit model	0.2%	0.6%	0.4%	Yes
$h_x h_y$ consistency (T0 vs V0)	0.1%	0.4%	0.4%	No
Bunch-by-bunch consistency	< 0.1% < 0.1%	0.1% 0.1%	0.1% 0.1%	No
Scan-to-scan consistency	0.2% 0.1%	0.1% 0.1%	0.5% 0.5%	No
Stability and consistency	1.5%	2.3%	1.6%	No
Total correlated	0.8% 1.0%	1.0% 1.2%	0.8% 1.0%	Yes
Total uncorrelated	1.6% 1.6%	2.4% 2.4%	1.8% 1.8%	No
Total	1.8% 1.9%	2.6% 2.7%	1.9% 2.1%	Partially

<u>Pb-Pb vs $s_{NN} = 5.02$ TeV (2015 + 2018)</u>	
Source	Uncertainty (%)
	VOM ZED
Statistical	0.09 0.04
Bunch intensity	0.8
$h_x h_y$ consistency (VOM vs ZED)	0.13
Length-scale calibration	1
Non-factorisation	1.1
Bunch-to-bunch consistency	0.1 0.4
Scan-to-scan consistency	1
Background subtraction	0.5 0.8
Magnetic non-linearities	0.2
Orbit drift	0.15
Beam-beam deflection and distortion	0.1
Fitting scheme	0.4
Total on visible cross section	2.1 2.2
Stability and consistency	0.7
Total on luminosity	2.2 2.3

ALICE-PUBLIC-2021-005

ALICE-PUBLIC-2021-001

Summary

- **Luminosity determination in ALICE**

- Luminosity

- a. Baseline of the normalization
- b. A source of non-negligible uncertainty for precision measurements

- vdM scan

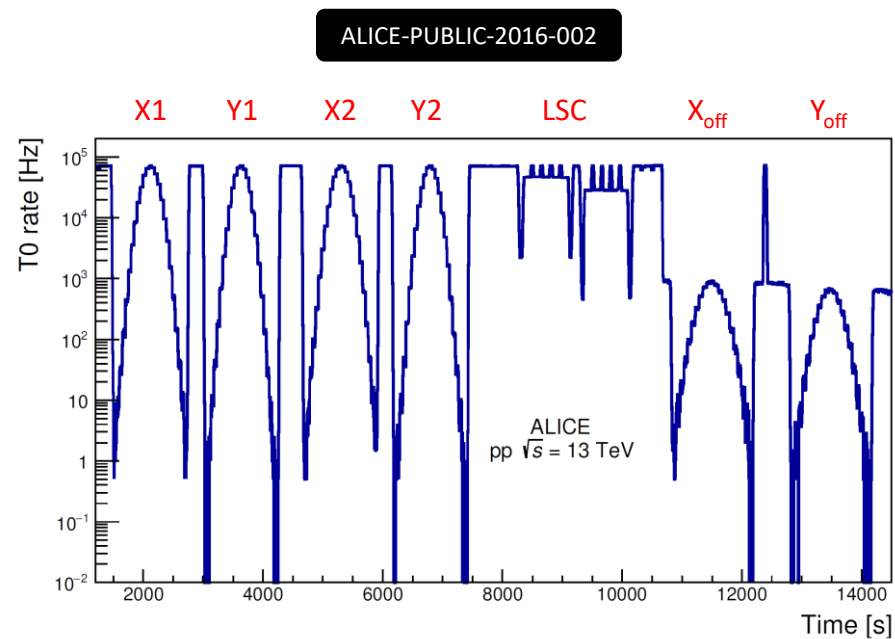
- a. Simple principle, but complicated calibrations and corrections
- b. Require dedicated data taking
- c. Rely on LHC instrumentation for beam control info and beam intensity, ALICE detectors (V0, T0, and ZN) for rate measurements

- 2015-2018 results for pp and Pb-Pb

- a. Source of the largest error:
stability and consistency for pp and non-factorization for Pb-Pb
- b. Total luminosity uncertainty for the analyses using 2015-2018 data:
~1.6% for pp and ~1.1% for Pb-Pb

Backup Scans in a vdM session

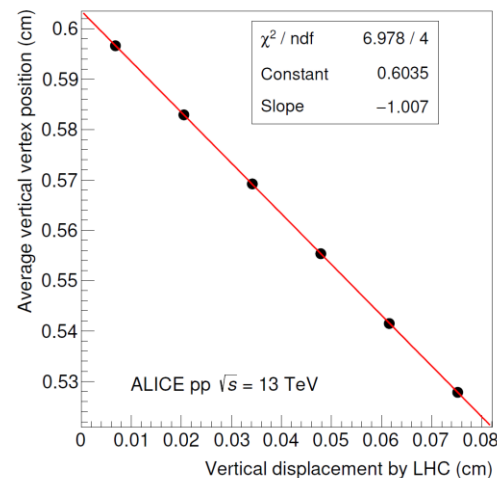
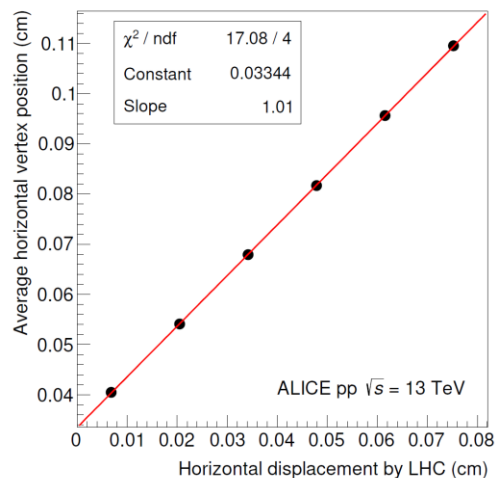
- **Type of scans in a vdM session**
 - Standard, symmetric scans (X1 - Y2)
 - a. Range: $[-6 \sigma_{beam}, +6 \sigma_{beam}]$
 - b. Step width: $0.5 \sigma_{beam}$ per step, total 25 steps
 - c. Elapsed time: $30 \text{ s} / \text{step}$
 - Length-scale calibration (LSC)
 - a. Step width: $\sim \sigma_{beam}$ per step, total 5 steps
 - b. Beams kept at $\sim \Sigma$
 - Offset scan
 - a. Typical offset $\sim 4 \sigma_{beam}$
 - b. Input to non-factorization fits



Backup Separation – LSC correction

- **Length scale calibration (LSC)**

- LHC operators control the beam separation by using the B-fields:
to check if the applied adjustment is properly converted to the desired length scale
- Specific LSC scan is performed during a vdM session:
 - a. The beams are moved simultaneously in one direction
 - b. The position after the move is measured by using ALICE trackers, to compare w/ LHC broadcasted separation
- The **calibration factor** is estimated as **the slope of the measured position vs. intended beam-spot position**
- The **effect of the correction on σ_{vis} is $< 2\%$** , but **the uncertainty is much less than that**



ALICE-PUBLIC-2021-005

Backup Run 2 results: pp $\sqrt{s} = 5$ TeV (2015, 2017)

pp $\sqrt{s} = 5$ TeV (2015), ALICE-PUBLIC-2016-005

Source	Uncertainty
Non-factorisation	1%
Orbit drift	< 0.1%
Beam-beam deflection	0.4%
Dynamic β^*	0.2%
Background subtraction	0.3% (T0), 1.1% (V0)
Pileup	0.7%
Length-scale calibration	1%
Fit model	0.7%
$h_x h_y$ consistency (T0 vs V0)	0.2%
Luminosity decay	0.7%
Bunch-by-bunch consistency	< 0.1%
Scan-to-scan consistency	0.5%
Beam centring	0.1%
Bunch intensity	0.4%
Total on visible cross section	2.05% (T0), 2.31% (V0)
Stability and consistency	0.4%
Total on luminosity	2.09% (T0), 2.34% (V0)

pp $\sqrt{s} = 5$ TeV (2017), ALICE-PUBLIC-2018-014

Source	Uncertainty
Non-factorisation	0.1%
Orbit drift	0.1%
Beam-beam deflection	0.5%
Dynamic β^*	0.2%
Background subtraction	0.2% (T0), 1.1% (V0)
Pileup	0.5%
Length-scale calibration	0.2%
Fit model	0.5%
$h_x h_y$ consistency (T0 vs V0)	< 0.1%
Luminosity decay	0.9%
Bunch-by-bunch consistency	< 0.1%
Scan-to-scan consistency	0.5% (T0), 0.4% (V0)
Beam centring	0.2%
Bunch intensity	0.4%
Total on visible cross section	1.5% (T0), 1.8% (V0)
Stability and consistency	1.1%
Total on luminosity	1.8% (T0), 2.1% (V0)

Backup Run 2 results: pp $\sqrt{s} = 13$ TeV (2015)

pp $\sqrt{s} = 13$ TeV (2015), ALICE-PUBLIC-2016-002

Source	Uncertainty
Non-factorisation	0.9%
Orbit drift	0.8%
Beam-beam deflection	0.8%
Dynamic β^*	0.3%
Background subtraction	0.1% (T0), 0.7% (V0)
Pileup	0.7%
Length-scale calibration	0.5%
Fit model	0.6%
$h_x h_y$ consistency (T0 vs V0)	0.6%
Luminosity decay	0.4%
Bunch-by-bunch consistency	< 0.1%
Scan-to-scan consistency	< 0.1%
Beam centring	< 0.1%
Bunch intensity	0.6%
Total on visible cross section	2.05% (T0), 2.16% (V0)
Stability and consistency	0.6% (isolated bunches) 2.7% (whole 2015)
Total on luminosity	2.2% (isolated bunches) 3.4% (whole 2015)

Backup

Run 2 results: p-Pb $\sqrt{s_{NN}} = 5.02$ TeV (2013) and 8.16 TeV (2016)

p-Pb $\sqrt{s_{NN}} = 5.02$ TeV (2013), CERN-PH-EP-2014-087

Uncertainty	p-Pp	Pb-p	Correlated between p-Pb and Pb-p
Transverse correlations	2.6%	2.3%	No
Bunch-by-bunch consistency	1.6%	-	No
Scan-to-scan consistency	0.5%	1.5%	No
Length-scale calibration	1.5%	1.5%	Yes
Background subtraction (V0 only)	0.5%	0.5%	Yes
Method dependence	0.3%	0.3%	No
Beam centering	0.3%	0.2%	No
Bunch size vs trigger	0.2%	0.2%	No
Bunch intensity	0.5%	0.5%	No
Orbit drift	0.4%	0.1%	No
Beam-beam deflection	0.2%	0.3%	Partially
Ghost charge	0.1%	0.2%	No
Satellite charge	<0.1%	0.1%	No
Dynamic β^*	<0.1%	0.1%	Partially
Total on visible cross section	3.5%	3.2%	
V0- vs T0-based integrated luminosity	1%	1%	No
Total on integrated luminosity	3.7%	3.4%	

p-Pb $\sqrt{s_{NN}} = 8.16$ TeV (2016), ALICE-PUBLIC-2018-002

Uncertainty	p-Pp	Pb-p	Correlated
Transverse correlations	0.6%	0.9%	No
Scan-to-scan consistency	0.6%	0.1%	No
Length-scale calibration	0.5%	0.8%	No
Background subtraction	0.5% (< 0.1%) V0 (T0)	0.6% (0.3%) V0 (T0)	Yes
Intensity decay	0.6%	0.7%	No
Method dependence	0.4% (0.5%) V0 (T0)	0.9% (0.6%) V0 (T0)	No
Beam centring	0.1%	0.1%	No
Bunch size vs trigger	0.2%	0.4%	No
Absolute DCCT calibration	0.3%	0.3%	No
Orbit drift	0.7%	0.3%	No
Beam-beam deflection	< 0.1%	0.4%	Partially
Ghost charge	< 0.1%	< 0.1%	No
Satellite charge	< 0.1%	< 0.1%	No
Dynamic β^*	< 0.1%	< 0.1%	Partially
Total on visible cross section	1.5% (1.5%) V0 (T0)	1.9% (1.7%) V0 (T0)	
V0 vs T0 integrated luminosity	1.1%	0.6%	No
Total on integrated luminosity	1.9% (1.8%) V0 (T0)	2.0% (1.8%) V0 (T0)	
Correlated part	0.5% (< 0.1%) V0 (T0)	0.7% (0.5%) V0 (T0)	
Uncorrelated part	1.8% (1.8%) V0 (T0)	1.9% (1.7%) V0 (T0)	